

THE SUN

THE IONOSPHERE  
THE TROPOSPHERE  
H<sub>2</sub>O  
O<sub>2</sub>

IMAGING ARTIFACTS

RADIO INTERFERENCES

UNSAMPLED (u,v) regions

CONFUSION

CALIBRATION

CLOSURE ERRORS

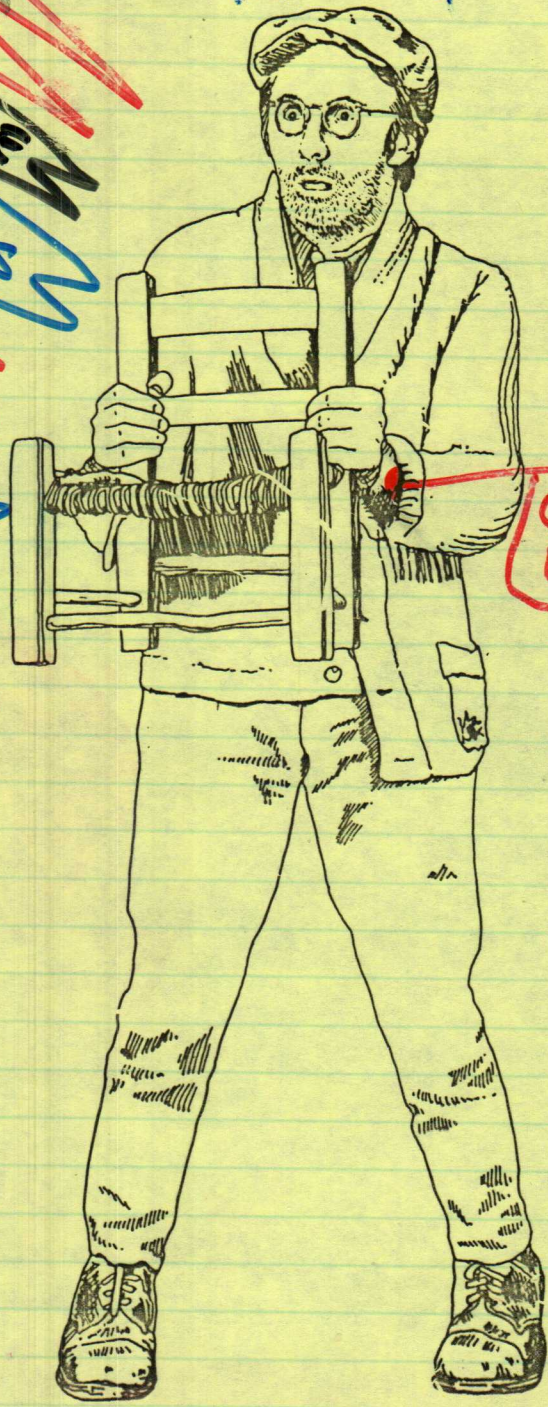
SENSITIVITY LIMITS

POLARIZATION

TIME SMEARING

POINTING ERRORS

BANDWIDTH SMEARING



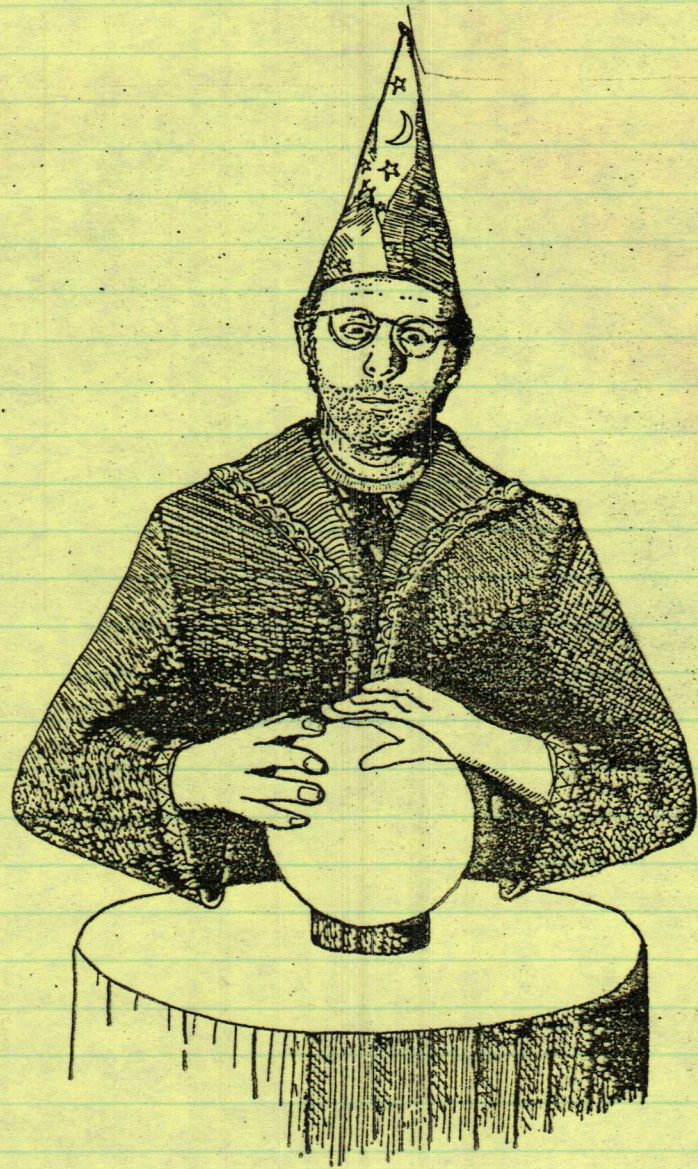
CLOCK ERRORS



19.

OBSERVING STRATEGIES I

HOW TO KEEP IT ALL UNDER CONTROL IF THERE'S A VLA OBSERVING PROPOSAL IN YOUR FUTURE .....



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R  
—  
↓

THE HITCH-HIKER'S GUIDE TO THE VLA

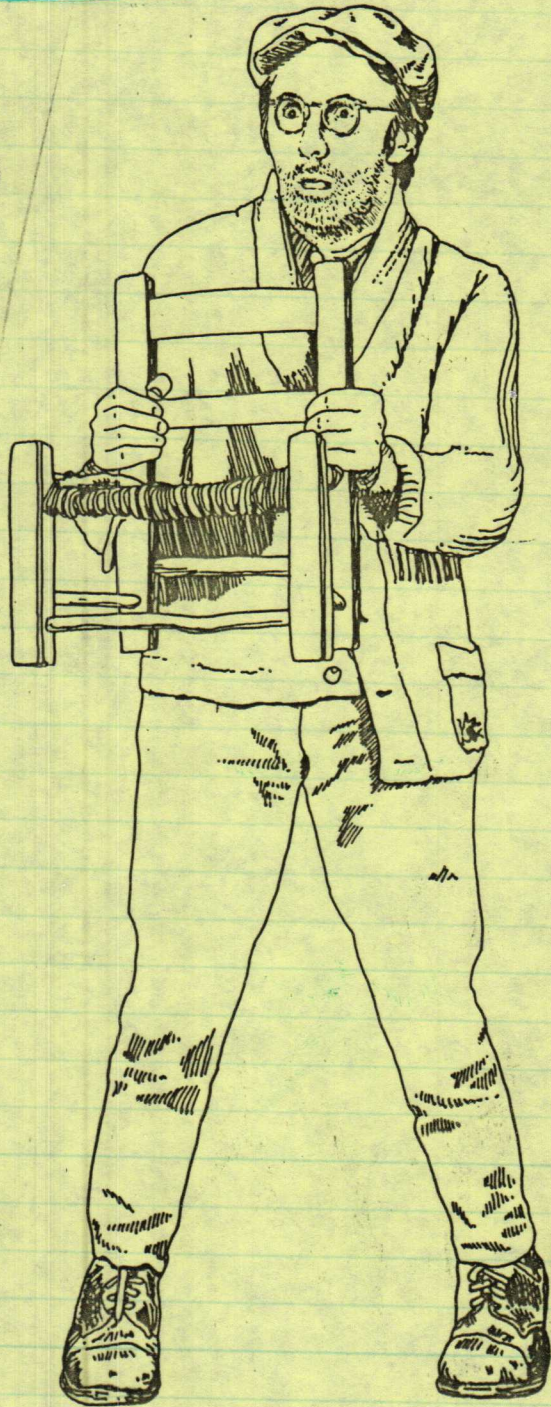


N.B. You may not know enough about your source to do exact sums everywhere here (if you need to know a great deal about it to do all of this). Where you don't have good #'s you have to wing it or use some extraphysical ideas, but it will <sup>also</sup> help you write the proposal to see where the missing pieces of this puzzle are.



VLA OBSERVING  
STRATEGY #1

DON'T  
PANIC  
!!





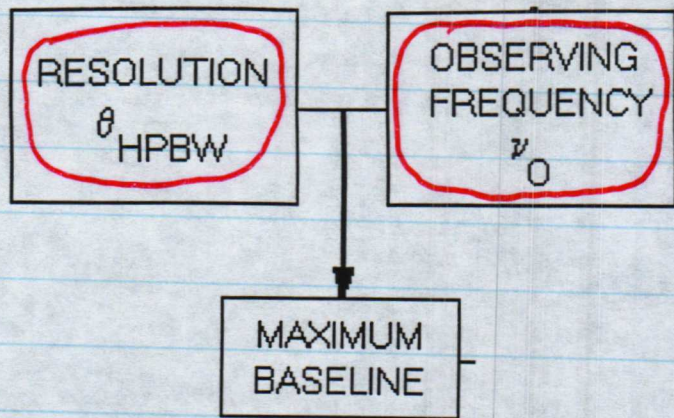


## Plan - Lecture 19

1. How to plan continuum observing
  - imaging goals → critical observing parameters
2. How to plan spectroscopic observing
  - a few key differences from continuum case
3. Calibration strategies (Walker, Fomalont, Brinks, Uson)
4. Proposal strategy (*if time*)
5. NRAO aids to strategy preparation
  - information sources
  - software



# STARTING-POINT ON CONTINUUM "TREE"







## Angular Resolution

- Specify  $\theta_{\text{HPBW}}$  — FWHM of synthesized beam
- How much is enough?
- Maximum useful  $\theta_{\text{HPBW}}$  may be set by
  - need to *separate* interesting structures
  - need to separate source from *confusion*
- Minimum useful  $\theta_{\text{HPBW}}$  may be set by
  - need to detect interesting *extended* structures
  - sensitivity limits
  - dynamic range limits
- Detection experiments: large  $u-v \rightarrow$  worse phase coherence





## Observing Frequency $\nu_0$

- Astronomical Factors

- source spectra (thermal *vs.* nonthermal)
- optical depth (see deeper at high  $\nu$ )
- polarimetry *Cotton*
  - \* Faraday thin at high  $\nu$
  - \* Faraday thick at low  $\nu$

- Instrumental Factors

- antenna efficiency *Napier*
- pointing *Beasley*
- receiver sensitivity *D'Addario*
- primary beam size *Napier*

- “Weather” at high frequencies *Fomalont*

- Interference at low frequencies  
*Ionosphere*

*Fomalont*





## Radio Frequency Interference

- Worst below 2 GHz
- Worst in compact configurations
- Worst at  $u = 0$  (fringe freq  $\nu_f = \omega_e u \cos \delta$ )
- Consult VLA RFI information before using non-standard frequencies
  - L Band table in lecture notes
  - VLA Observational Status Report
  - <http://www.nrao.edu/doc/vla/interference/>





## Resolution Formulae

- VLA  $\theta_{\text{HPBW}} = 1.''3 \times \frac{1.5}{\nu_0} \times 3.3^{n-1}$ 
  - n=1 for A configuration
  - n=2 for B configuration
  - n=3 for C configuration
  - n=4 for D configuration
  - $\nu_0$  in GHz
- Beam area  $\Omega_s = 1.13\theta_{\text{HPBW}}^2$



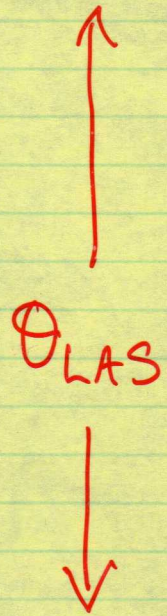
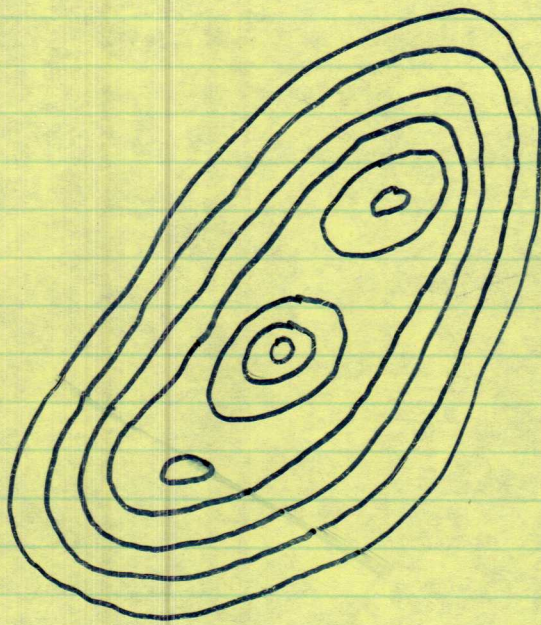


## Resolution Strategy

- Try *conservative*  $\theta_{\text{HPBW}}$  first
  - maximum that is enough to separate *interesting* features
- Work down decision tree with this  $\theta_{\text{HPBW}}$
- Find needed total integration time  $t_{\text{int}}$
- If short, smaller  $\theta_{\text{HPBW}}$  may work too!
- If long, rethink!



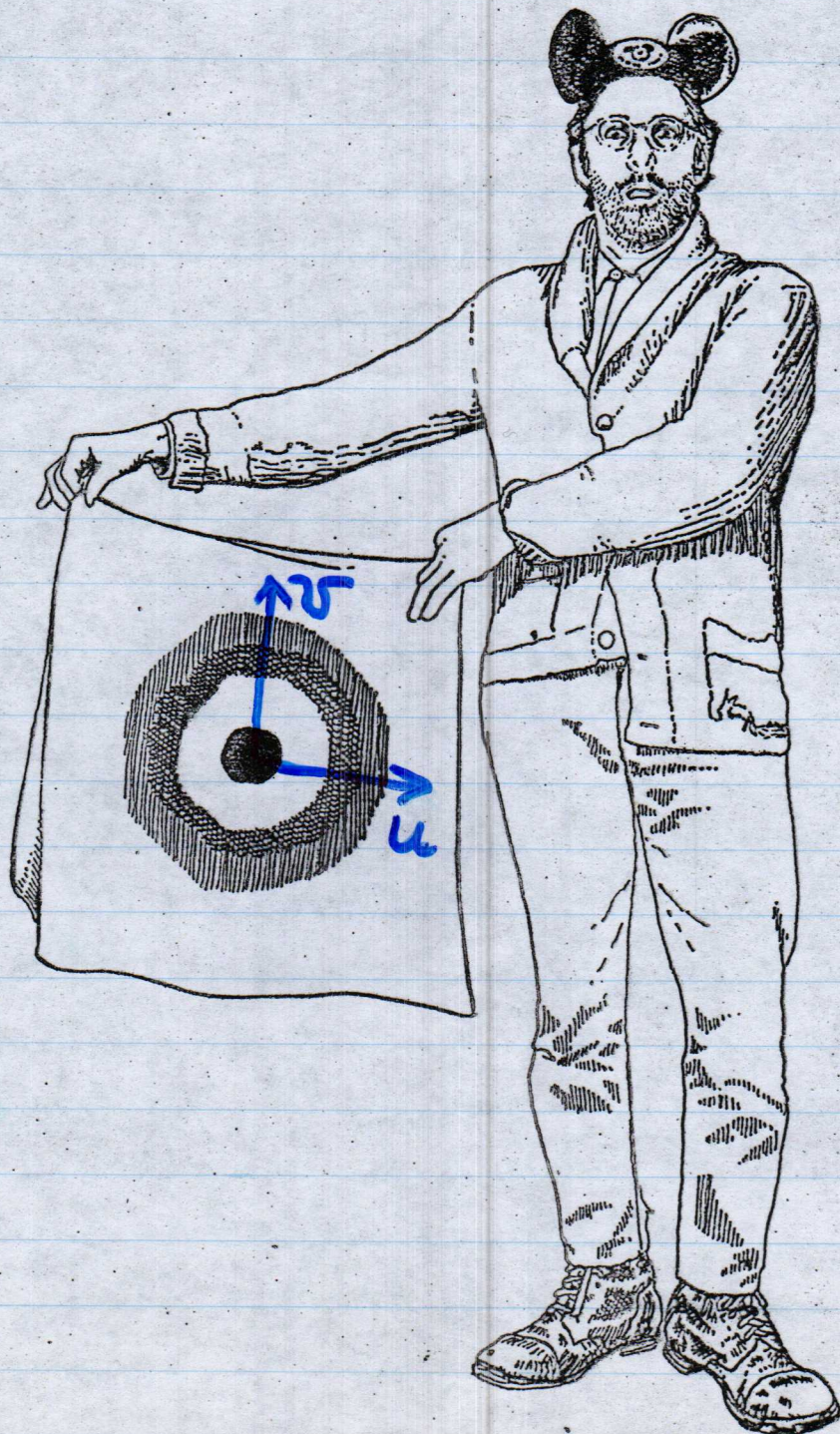
SYNTHESIZED  
● BEAM  
 $\theta_{HPBW}$



$$\theta_{HPBW} \rightarrow \text{LONGEST baseline (km)} = \frac{2 \lambda (\text{cm})}{\theta_{HPBW} (")}$$
$$\theta_{LAS} \rightarrow \text{SHORTEST baseline (km)} = \frac{\lambda (\text{cm})}{\theta_{LAS} (")}$$



# CHOICE OF CONFIGURATION







## Longest and Shortest Baselines

- $\theta_{\text{HPBW}}$  and  $\nu_0 \rightarrow$  longest baseline needed

- Longest  $a(\text{km}) \approx \frac{2\lambda_0(\text{cm})}{\theta_{\text{HPBW}}(\text{arcsec})}$

- Don't forget about *shortest!!*

- What is largest structural scale  $\theta_{\text{LAS}}$  to be imaged?

- Shortest  $a(\text{km}) \approx \frac{\lambda_0(\text{cm})}{\theta_{\text{LAS}}(\text{arcsec})}$  ( $\sim 50\%$  response)

- One VLA configuration  $\rightarrow \approx 20\text{--}40:1$  in  $\theta_{\text{LAS}}/\theta_{\text{HPBW}}$

- Fitting to actual VLA configurations:

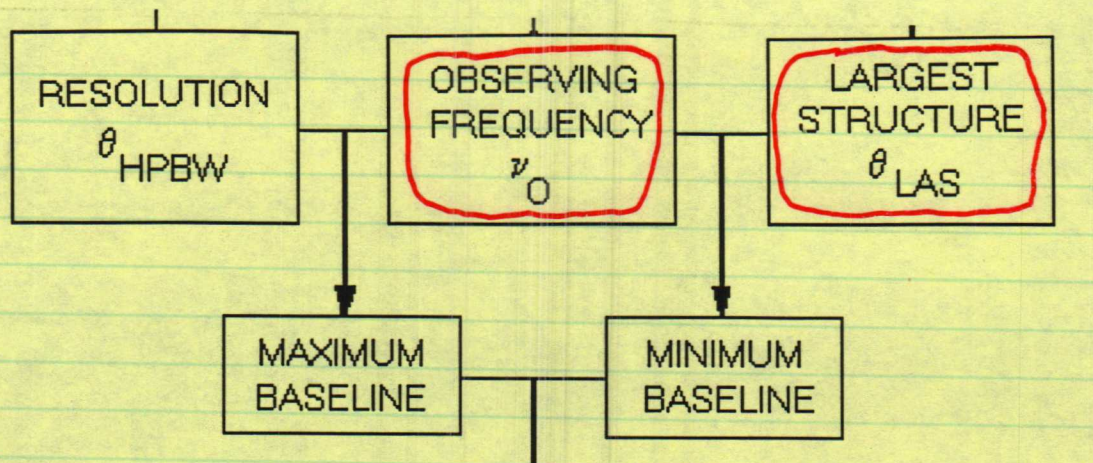
- First pick widest configuration from  $\theta_{\text{HPBW}}, \nu_0$

- VLA  $\theta_{\text{HPBW}} = 1.''3 \times \frac{1.5}{\nu_0} \times 3.3^{n-1}$  A  $n=1$   
B  $n=2$  etc.....

- Does this contain shortest baseline needed?

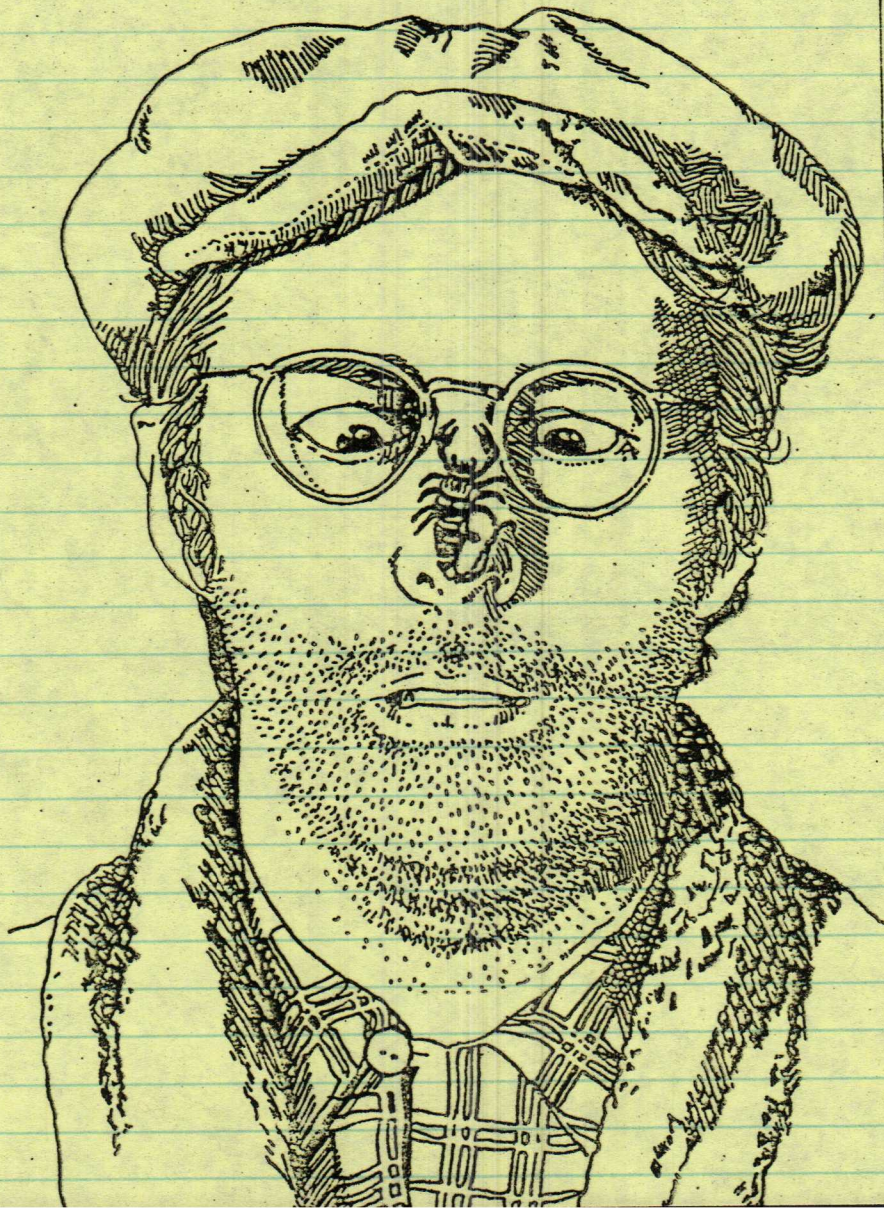
- If not, use *multiple* (adjacent) configurations



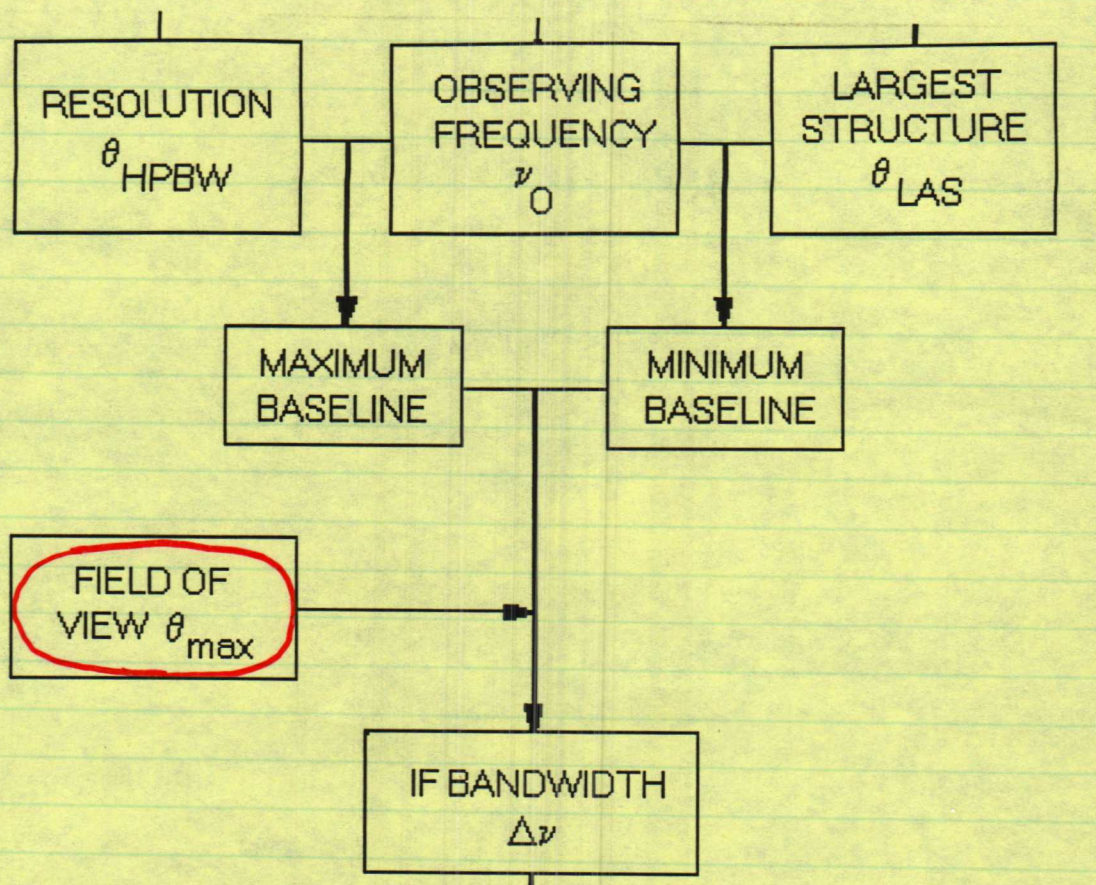




# FIELD OF VIEW RESTRICTIONS











## Field of View Considerations

- Consider beam smearing  $\equiv$  loss of point source response from:

- finite IF bandwidth  $\Delta\nu$

Beasley, Cornwell, Perley

- finite visibility averaging time  $\tau_a$

Perley

for features away from delay and phase tracking center.

- Decide how far— $\theta_{\max}$ —from d.t.c., p.t.c. you must image with some ( $\leq m\%$ ) distortion

- Use  $m, \theta_{\max}$  to find  $\beta_{\max}$  for bandwidth smearing (scales as  $\beta = [\Delta\nu/\nu] \times [\theta_{\max}/\theta_{\text{HPBW}}]$ )

Old Lecture 13  
Perley

- $\Delta\nu_{\max} = \beta_{\max} \times \nu_0 \times \theta_{\text{HPBW}} / \theta_{\max}$

- Choose  $\Delta\nu < \Delta\nu_{\max}$  from allowed settings

- Choose  $\tau_a < \text{"equivalent distortion time"} \tau_{\Delta\nu}$





## Useful Formulae for Distortion Effects

Old Lecture  
13 in "White  
Book"

Use  $\frac{I}{I_0}$  (observed/undistorted intensity of point source)

- Bandwidth smearing, square band, Gaussian  $u-v$  taper:

– Exact:  $\frac{I}{I_0} = \frac{\sqrt{\pi}}{\gamma\beta} \operatorname{erf} \frac{\gamma\beta}{2}$  ( $\gamma \equiv 2\sqrt{\ln 2} = 1.665$ )

– Low-order:  $\frac{I}{I_0} \approx 1 - \frac{1}{3} \left( \frac{\gamma\Delta\nu\theta}{2\nu_0\theta_{\text{HPBW}}} \right)^2$

- Low-order time average smearing (approx):

$$\frac{I}{I_0} \approx 1 - \frac{\gamma^2 \omega_e^2 \tau_a^2}{12} \left( \frac{\theta}{\theta_{\text{HPBW}}} \right)^2$$

- Rough equivalence between distortions:

$$\tau_{\Delta\nu} \approx \frac{\Delta\nu}{\omega_e \nu_0} = 1.375 \times 10^4 \frac{\Delta\nu}{\nu_0} \text{sec}$$

$$\omega\tau \approx \frac{\Delta\nu}{\nu}$$

– independent of baseline length,  $\theta_{\text{max}}$



10%  
Loss

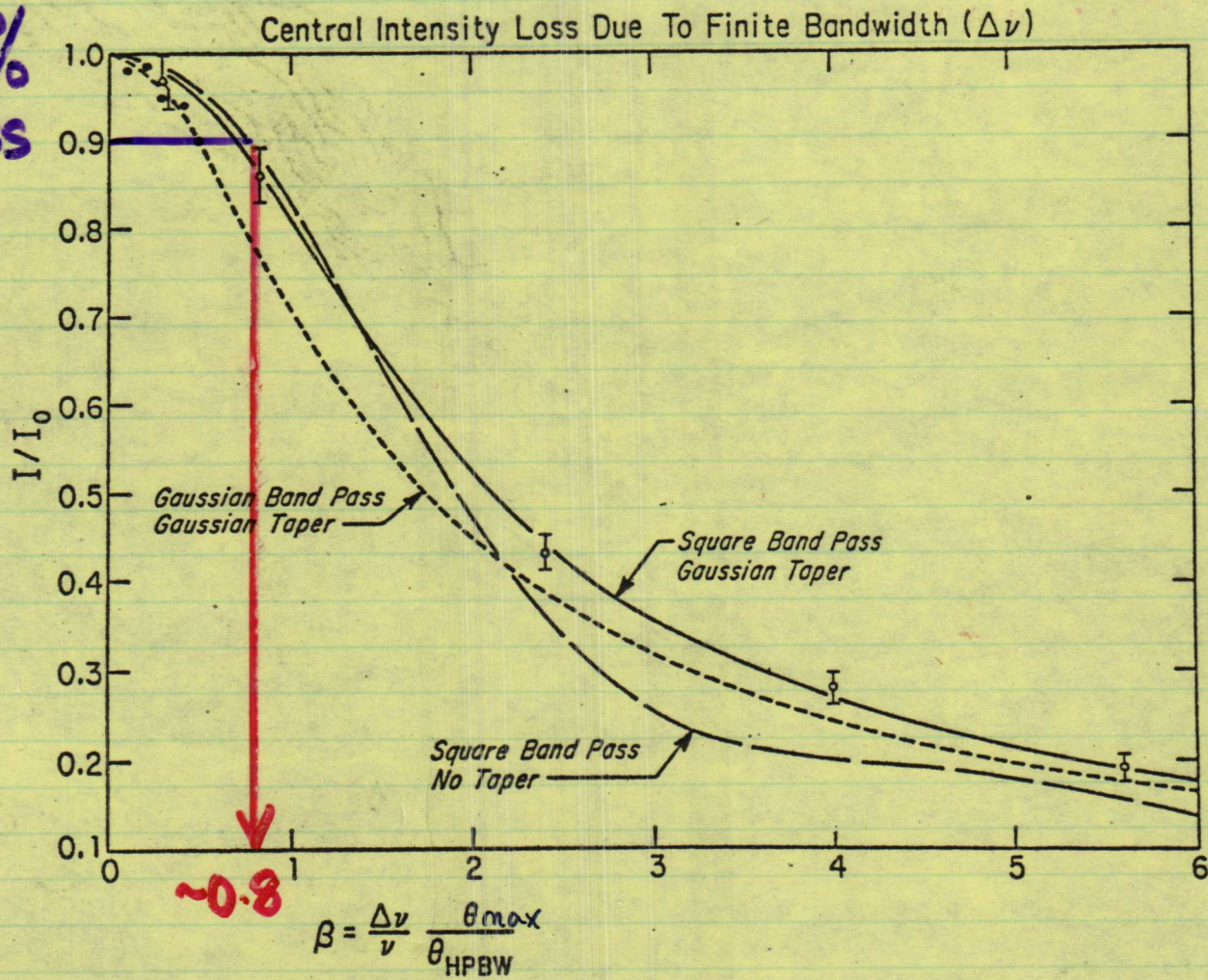
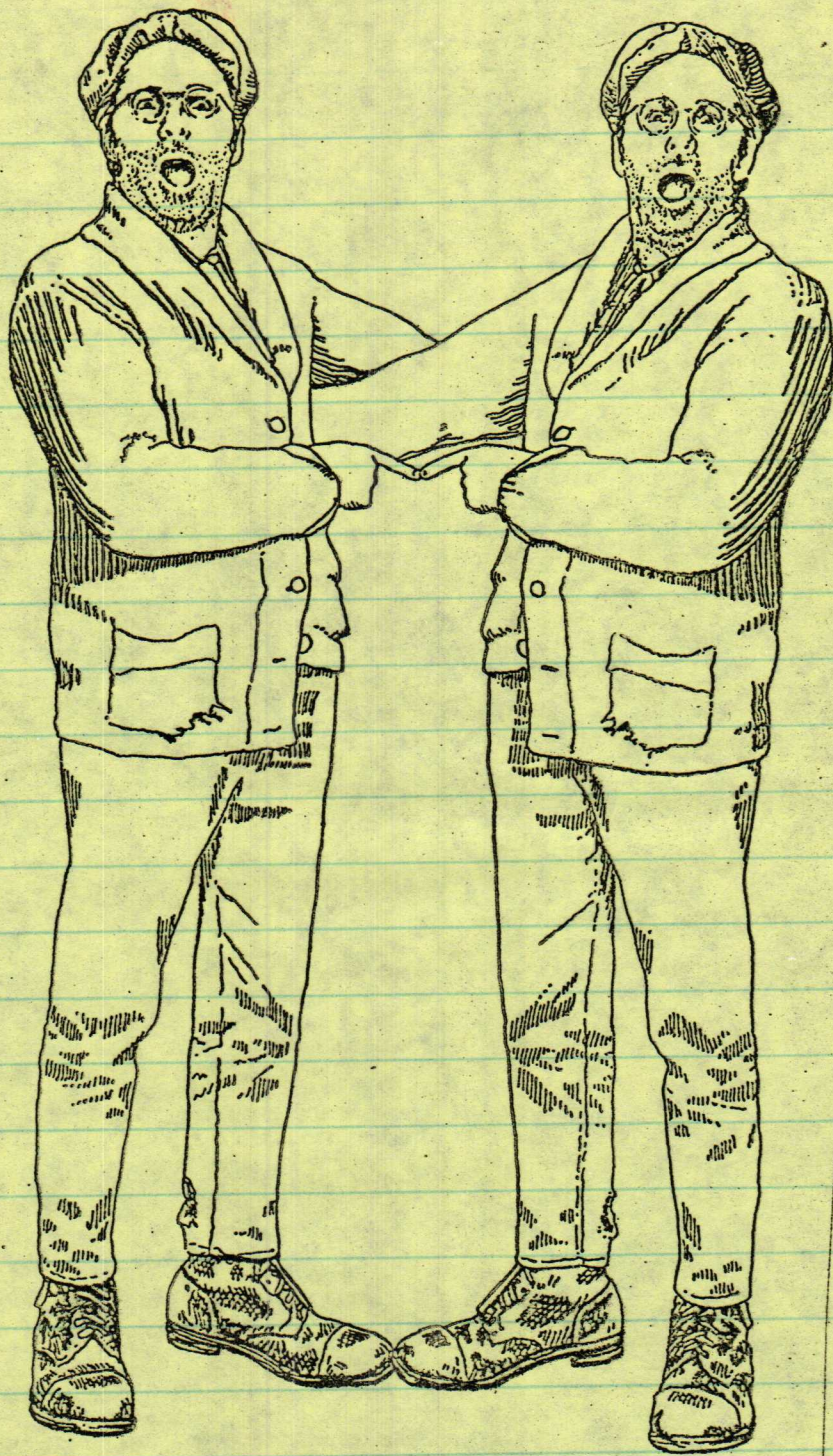


Figure 14-2: Central intensity loss, due to finite IF bandwidth  $\Delta\nu$ , plotted as a function of the dimensionless parameter  $\beta$ .  $\theta$  is angular distance of the feature from the phase center, in the same units as the beamwidth  $\theta_{HPBW}$ .





CONFUSION and  
ALIASING





## Confusion

*i.e.*, sources you don't want but which are in your field of view. They create two types of problem:

- Sidelobes of confusing sources limit r.m.s. of image and will not deconvolve if aliased.
- "Wrong source" in detection experiment.

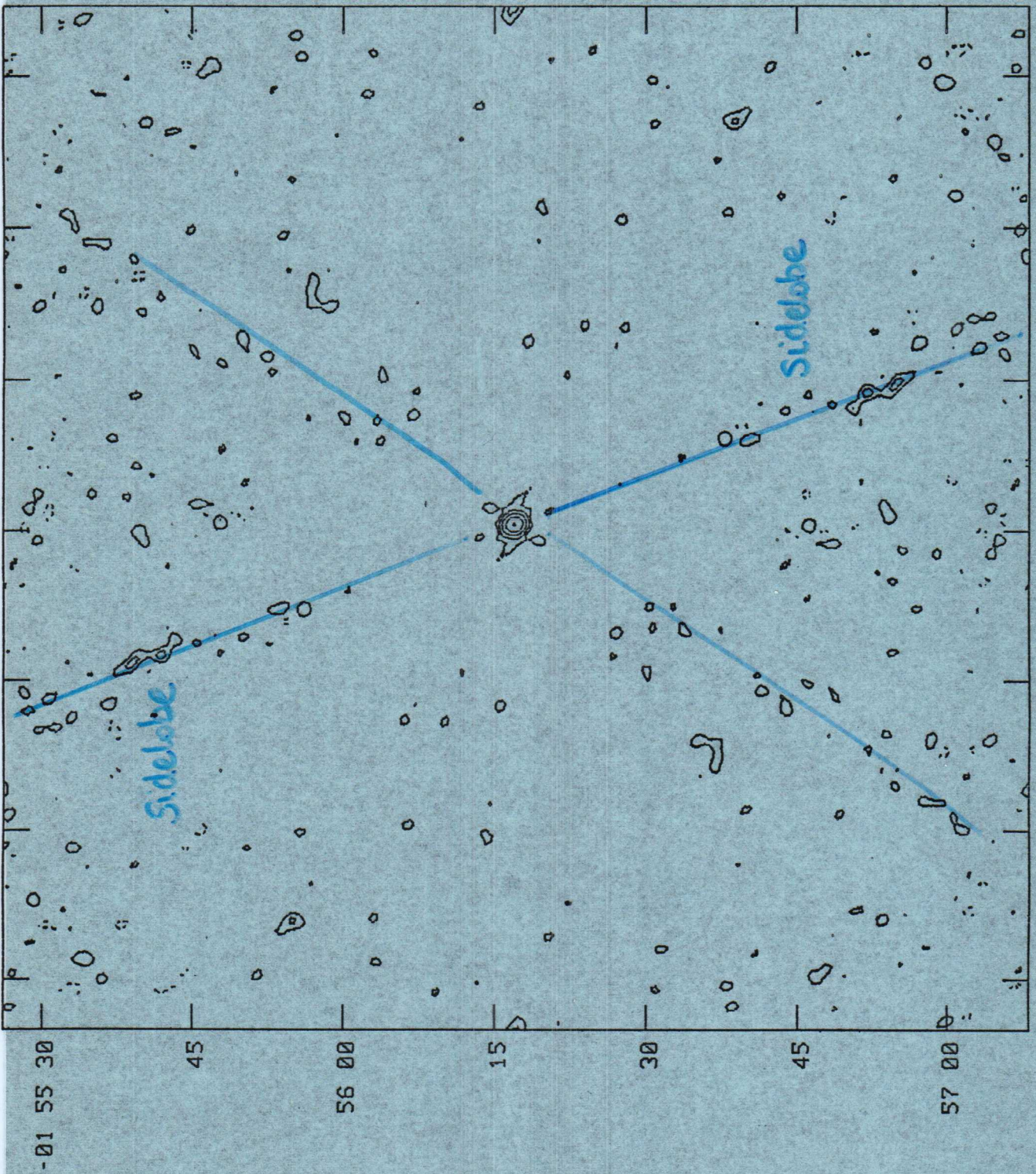
Cornwell

Confusion is worst:

- at low  $\nu$  (bigger primary beam)
  - 327 MHz, expect several Jy in primary beam
  - 1.5 GHz, expect a 110 mJy source in primary beam
  - 4.9 GHz, expect a 2 mJy source in primary beam
- in compact arrays (less bandwidth suppression)
- at low galactic latitudes (more "junk" in sky)



0336-019 IPOL 1464.900 MHZ SHIFT.IMAP.5



-01 55 30

45

56 00

15

30

45

57 00

03 37 02

01

00

36 59

58

57

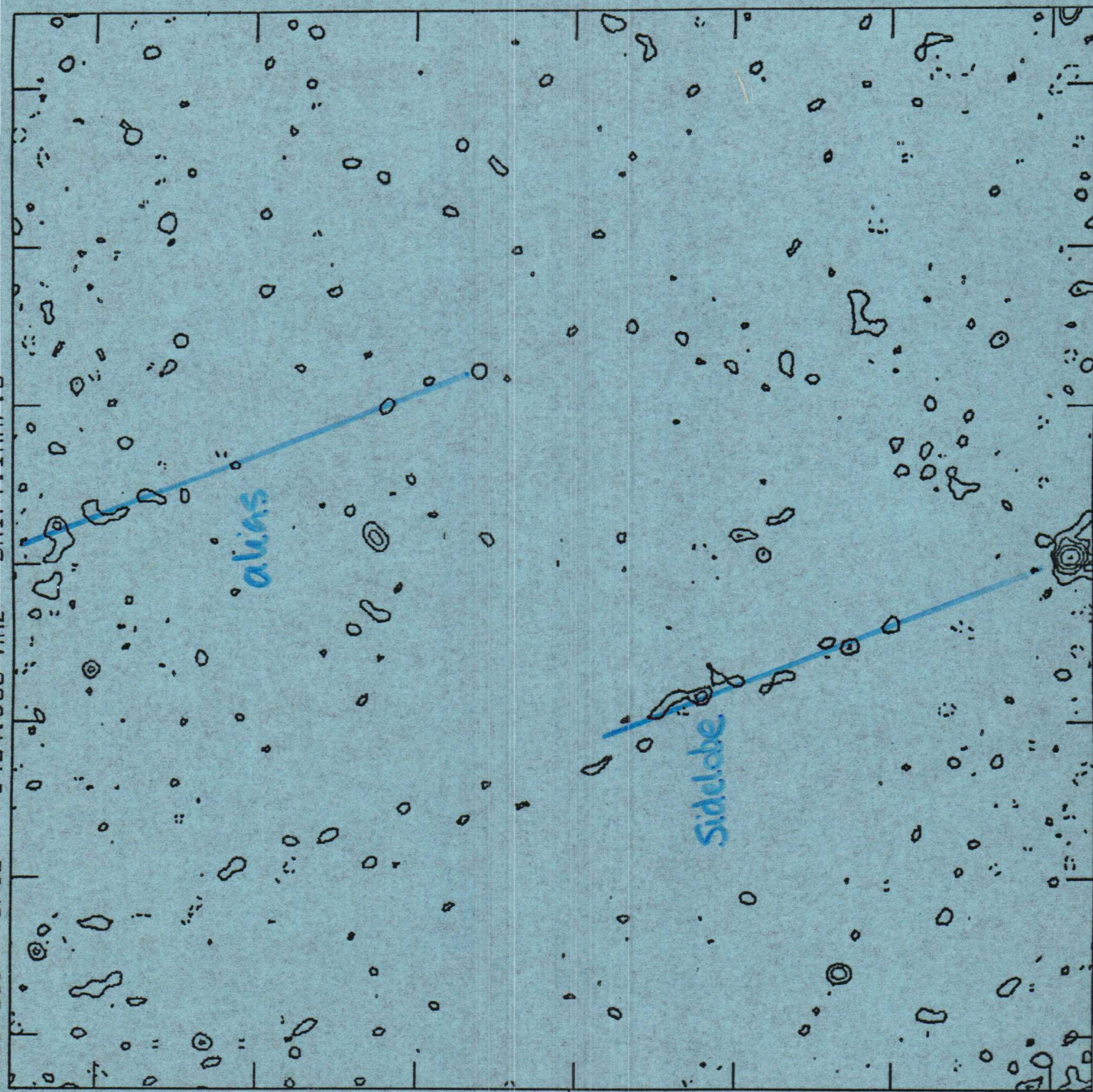
56

DECLINATION

RIGHT ASCENSION  
PEAK FLUX = 0.1866E+01 JY/BEAM  
LEUS = 0.1866E-01 \* (-12.5, -6.3, 6.3,  
12.5, 25.0, 50.0, 95.0)



0336-019 IPOL 1464.900 MHZ SHIFT.IMAP.6



-01 54 45

55 00

15

30

45

56 00

15

DECLINATION

56

57

58

59

00

01

02

03

RIGHT ASCENSION

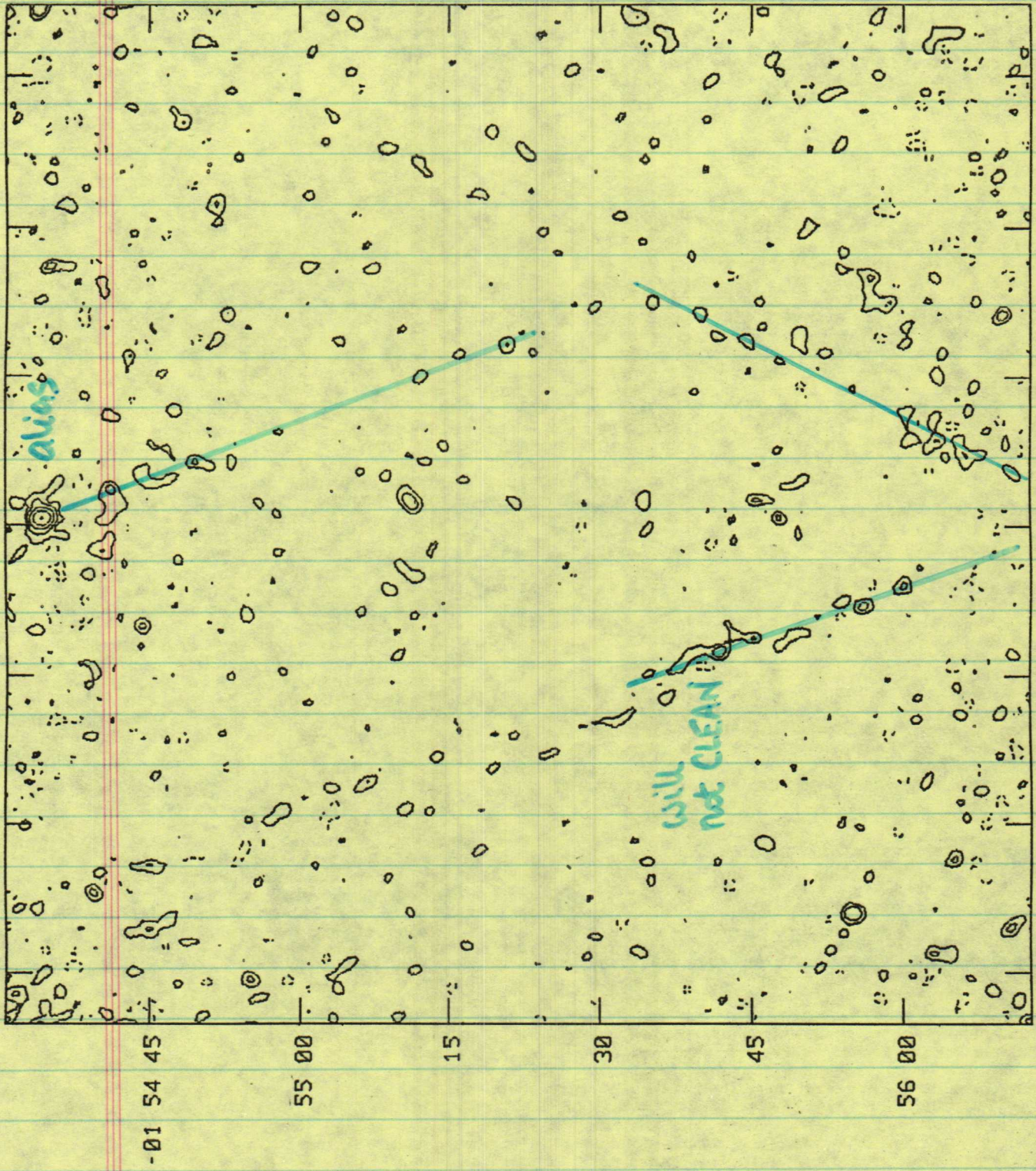
PEAK FLUX = 0.1892E+01 JY/BEM

LEVS = 0.1892E-01 \* (-12.5, -6.3, 6.3,

12.5, 25.0, 50.0, 95.0)



0336-019 IPOL 1454.900 MHZ SHIFT. IMAP. 12



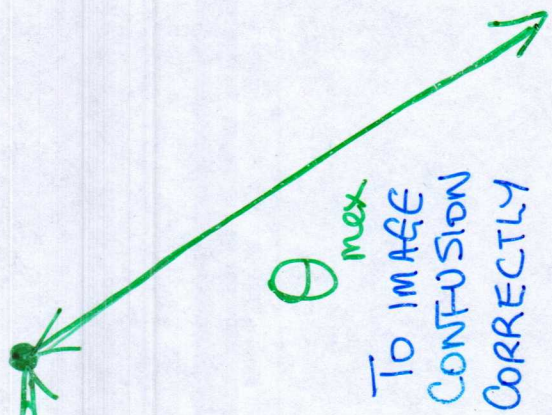
01 02 03 37 02 01 00 36 59 58 57 56

RIGHT ASCENSION  
PEAK FLUX = 0.1666E+01 JY/BAM  
LEUS = 0.1666E-01 \* (-12.5, -6.3, 6.3,  
12.5, 25.0, 50.0, 95.0)

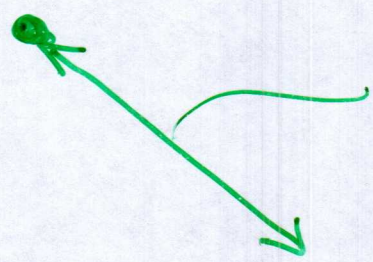
DECLINATION



DELAY  
TRACKING  
CENTER



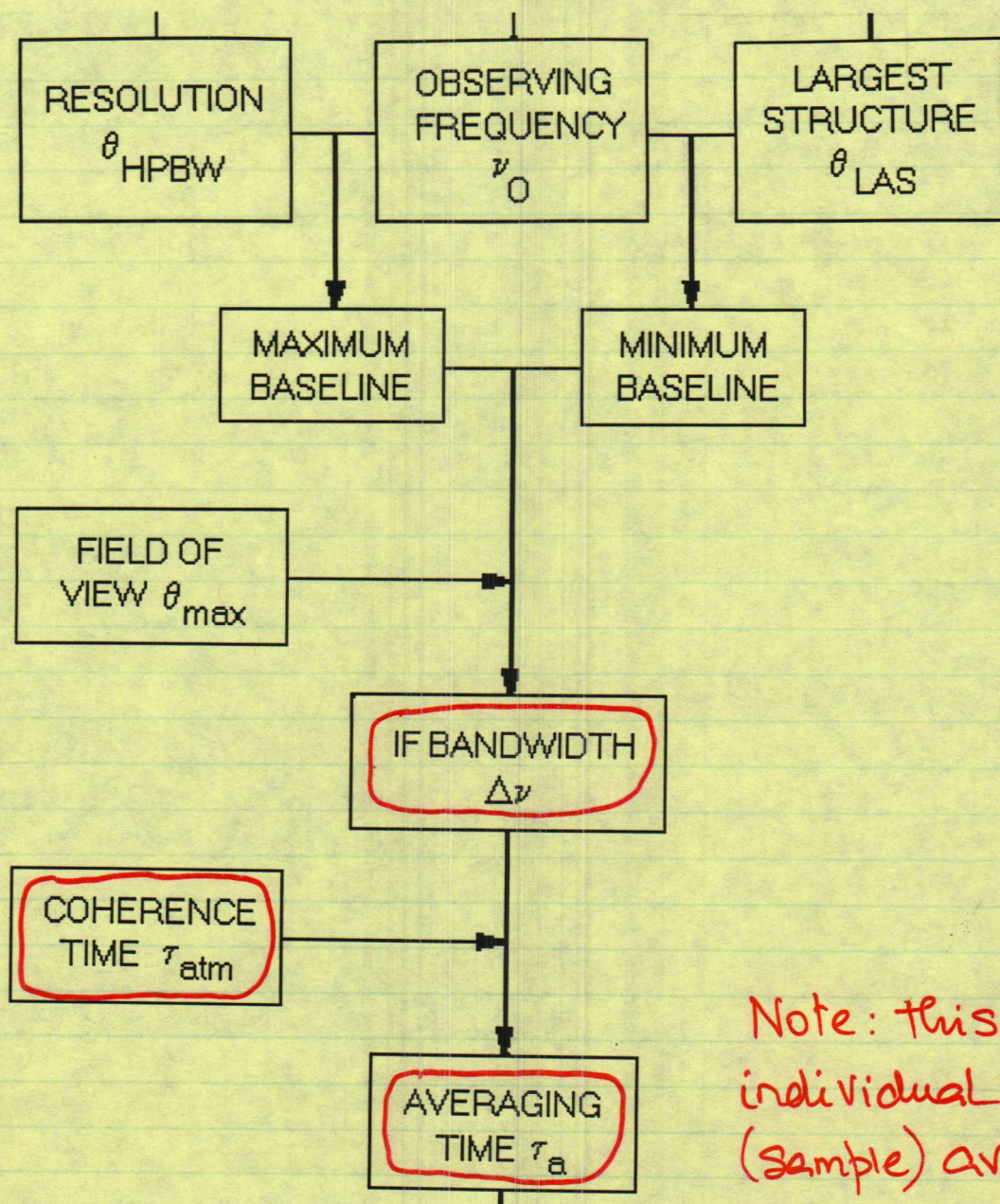
$\theta_{max}$   
TO IMAGE  
CONFUSION  
CORRECTLY



$$\theta_{max} \sim \frac{1}{2} \theta_{LAS}$$

IF ONLY INTERESTED  
IN DECONVOLVING SID ELOBES  
OF CONFUSION





Note: this is the individual visibility (sample) averaging time, NOT total integration time!

---



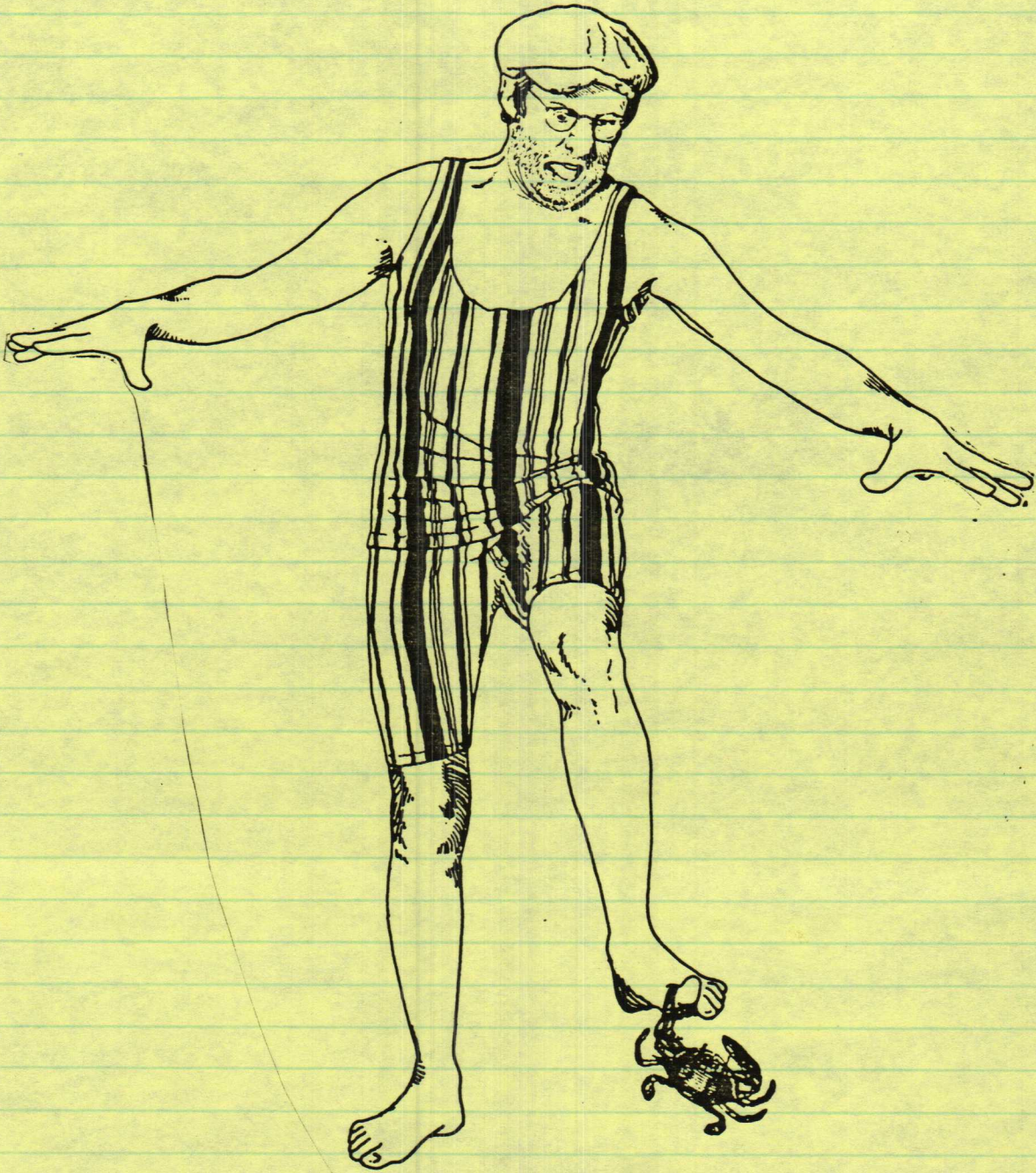


## Averaging Time $\tau_a$

- No longer than bandwidth distortion equivalent
- No longer than expected phase coherence time
- In range selectable at VLA ( $>1.67$  sec)!

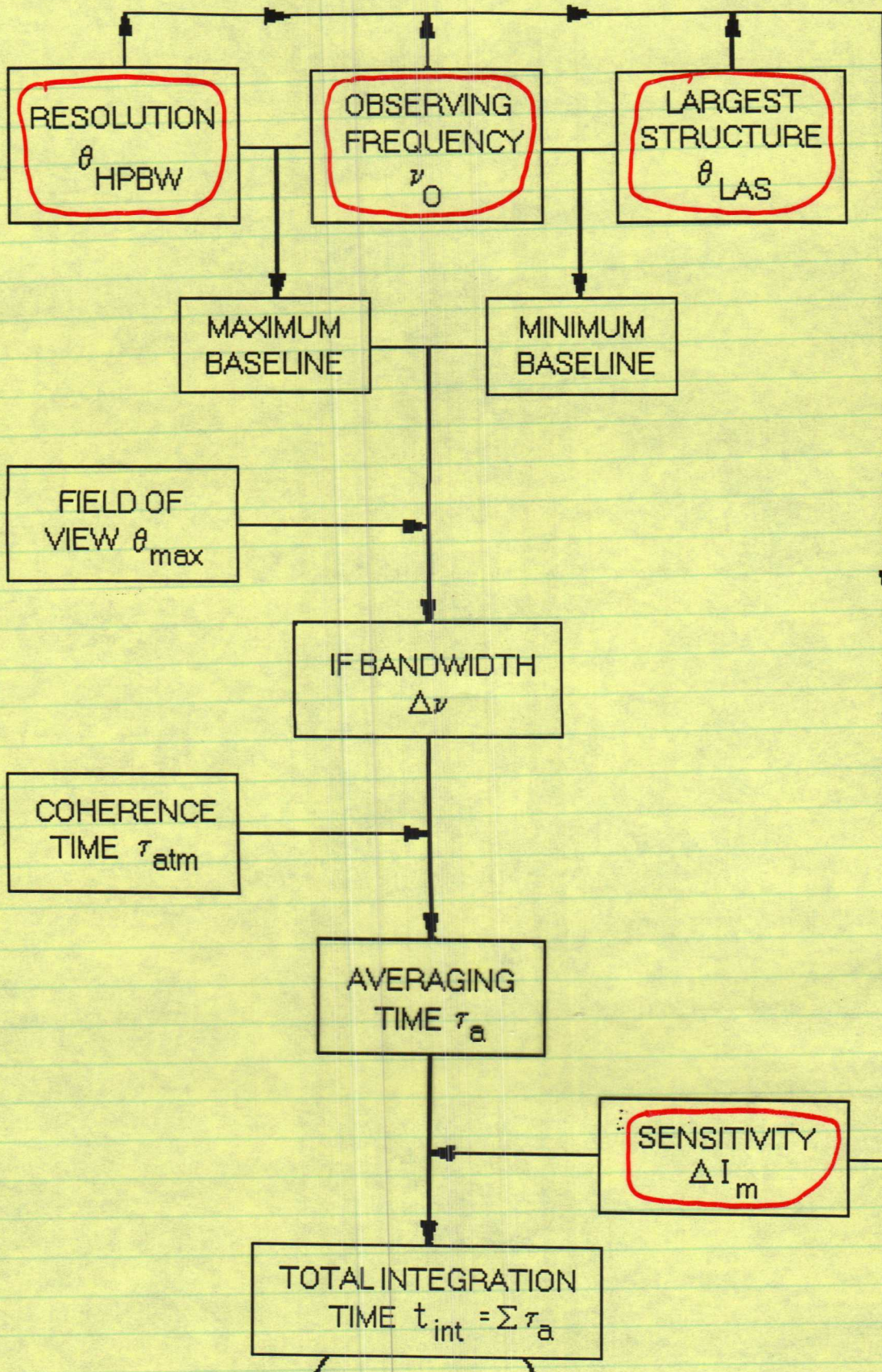
Cornwell  
formalont





SENSITIVITY









## Sensitivity

Now specify the r.m.s. noise  $\Delta I_m$  needed in the final image. (mJy per beam area)

- Consider resolution of extended structures!
- Use polarized intensity if doing polarimetry!

Knowing the bandwidth  $\Delta\nu$  and the sensitivity parameter  $\Delta S$  of the system you will use at frequency  $\nu_0$ , compute the total integration time  $t_{\text{int}}$  needed to reach  $\Delta I_m$ .

Is the result reasonable?

- "yes"  $\rightarrow$  you're done!
- "no"  $\rightarrow$  rethink!





## The Sensitivity Equation

$$\Delta I_m = F_w \Delta S / \sqrt{\frac{nN(N-1)}{2} t_{\text{int}} \Delta \nu} \text{ where}$$

D'Addario

- $N$  is the number of antennas in the array
- $n$  is the number of IF's contributing (usually 2) <sup>maybe 4</sup>
- $t_{\text{int}}$  is in seconds
- $\Delta \nu$  is in MHz
- $F_w$  is 1.0—1.5 depending on  $u$ - $v$  weighting <sup>Cornwell</sup>
- $\Delta S$  is the single-interferometer sensitivity per sec per MHz

Get  $\Delta S$  for your  $\nu_0$  from VLA documents:

- these lecture notes (current)
- VLA Observational Status Report (future)





HOW LONG WILL IT TAKE

?

$t_{int} \ll 4 \text{ hr}$

→

SNAPSHOTS possible?

$t_{int} \sim 4 \text{ hr}$

→

full HA track?

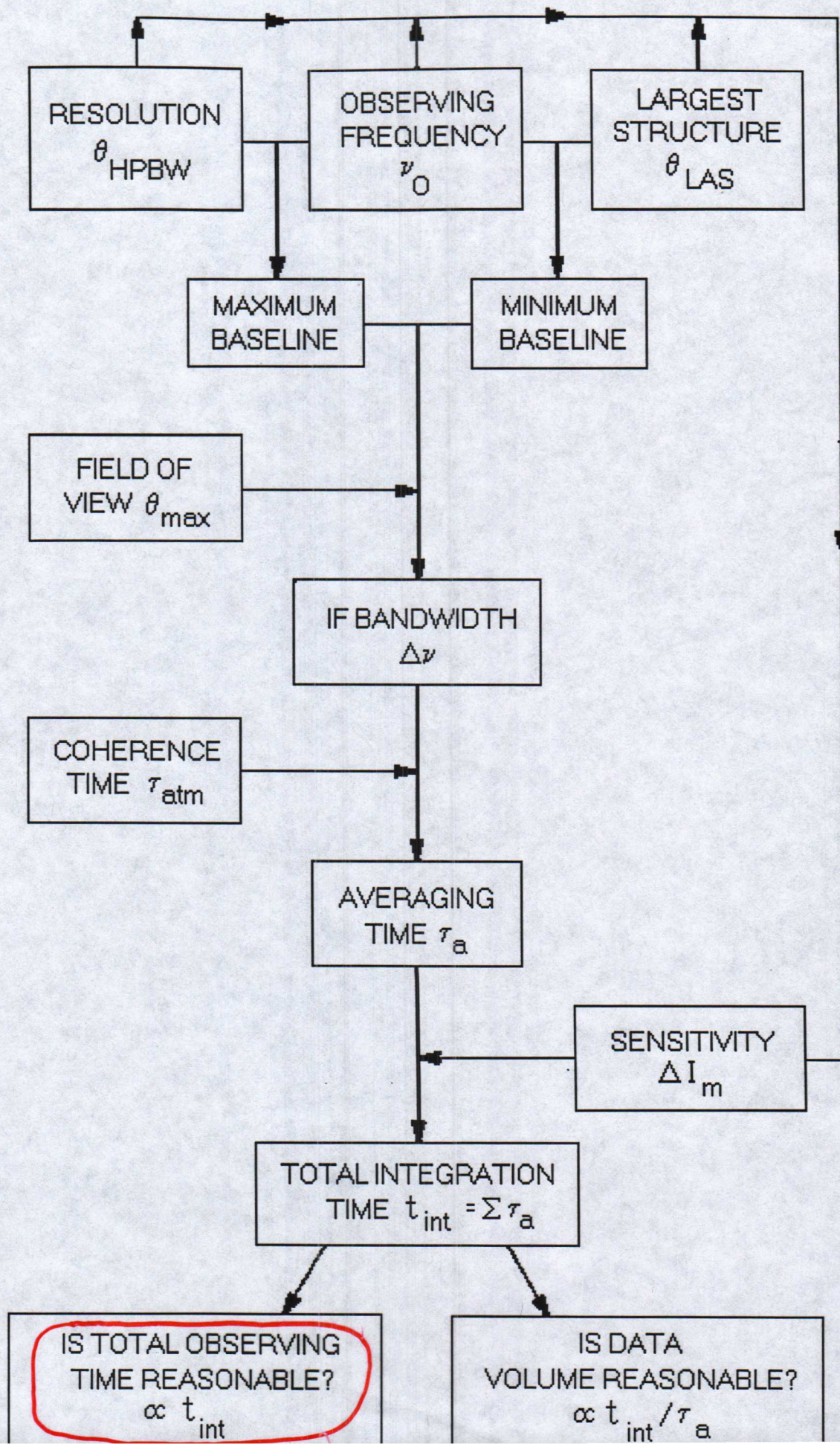
$t_{int} > \underline{12 \text{ hr}}$

→

rethink?

OR WRITE A VERY  
GOOD CASE IN  
PROPOSAL!!!







# "SNAPSHOT" IMAGING

"Instantaneous" (1-5 min) coverage useful for:

many bright compact sources in  
shortest possible time

## LIMITATIONS

- 1) Sensitivity (short  $t_{int}$ )
- 2) High sidelobes of dirty beam ("snowflake")
  - super-uniform weighting useful
  - best in unconfused fields (high  $\nu_0$ , high  $b$ )
  - may still need to make large images
- 3) Limited reliable field of view ("holes" in coverage)  
angular scale
- 4) Short programs cannot do polarization (D,  $\chi$ )  
calibration as well as long ones
  - may need to co-ordinate calibration with other observers

Best strategies: observe within  $\pm 2^h$  of meridian  
reduce with { super-uniform weight  
ungridded subtraction

AIPS: MX, IMAER



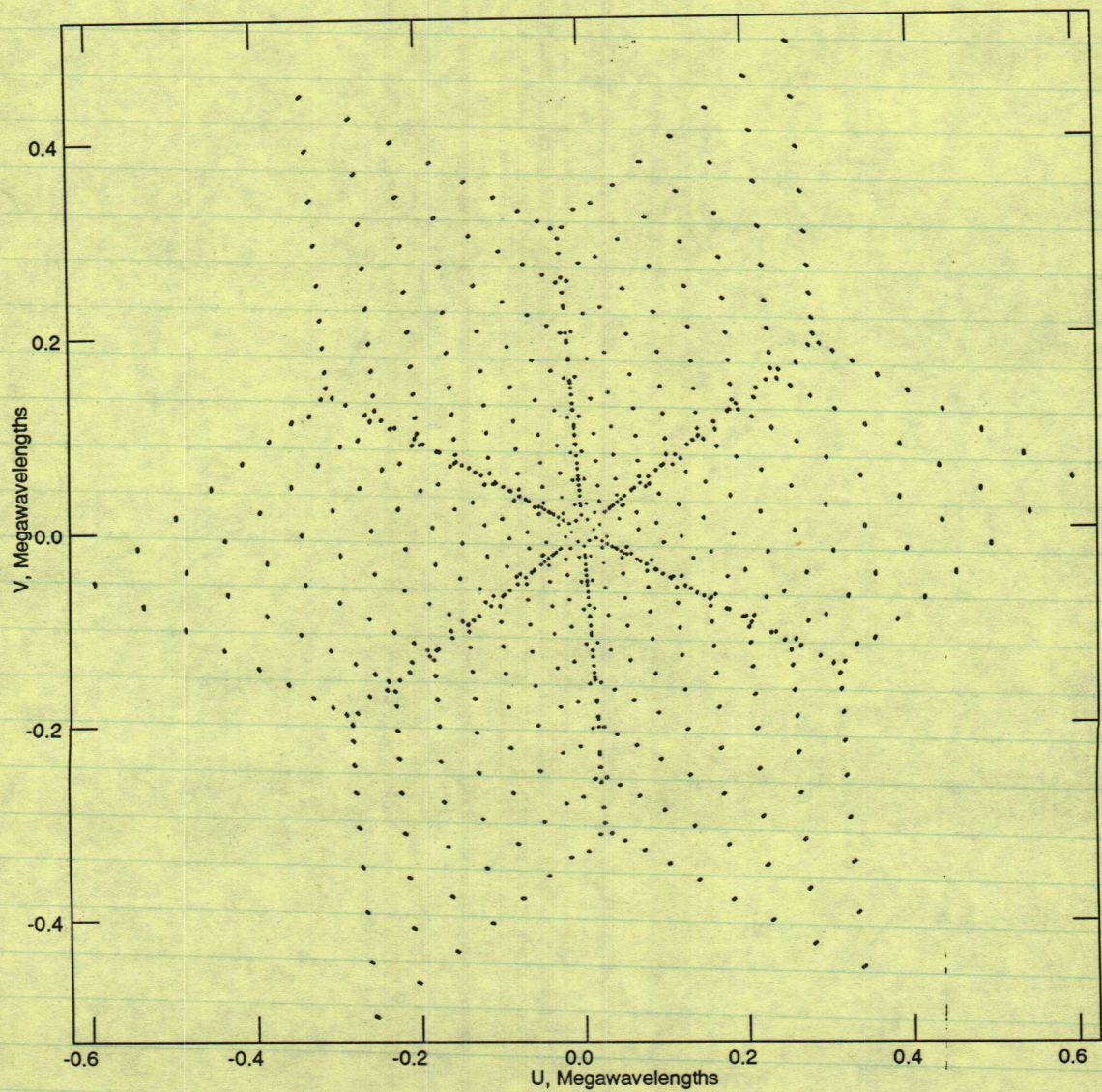


Figure 6: The  $u-v$  plane coverage at 4.9 GHz for instantaneous sampling of a source at  $\delta = 30^\circ$  and hour-angle  $0^h$  with the VLA in the A configuration.





CONSIDER  
COMBINING  
SEVERAL CONFIGURATIONS

.....





## Mixed Configurations

- Multiple configurations for large  $\theta_{\text{LAS}}/\theta_{\text{HPBW}}$  ( $>40:1$ )
  - Add single-dish and mosaicing for *huge* sources? Holdaway,  $\theta_{\text{LAS}} \gtrsim \text{FWHM of primary beam!}$
- Long North Arm for  $\delta < -15^\circ$
- Sub-arrays inefficient (unless synoptic multi- $\nu$ )





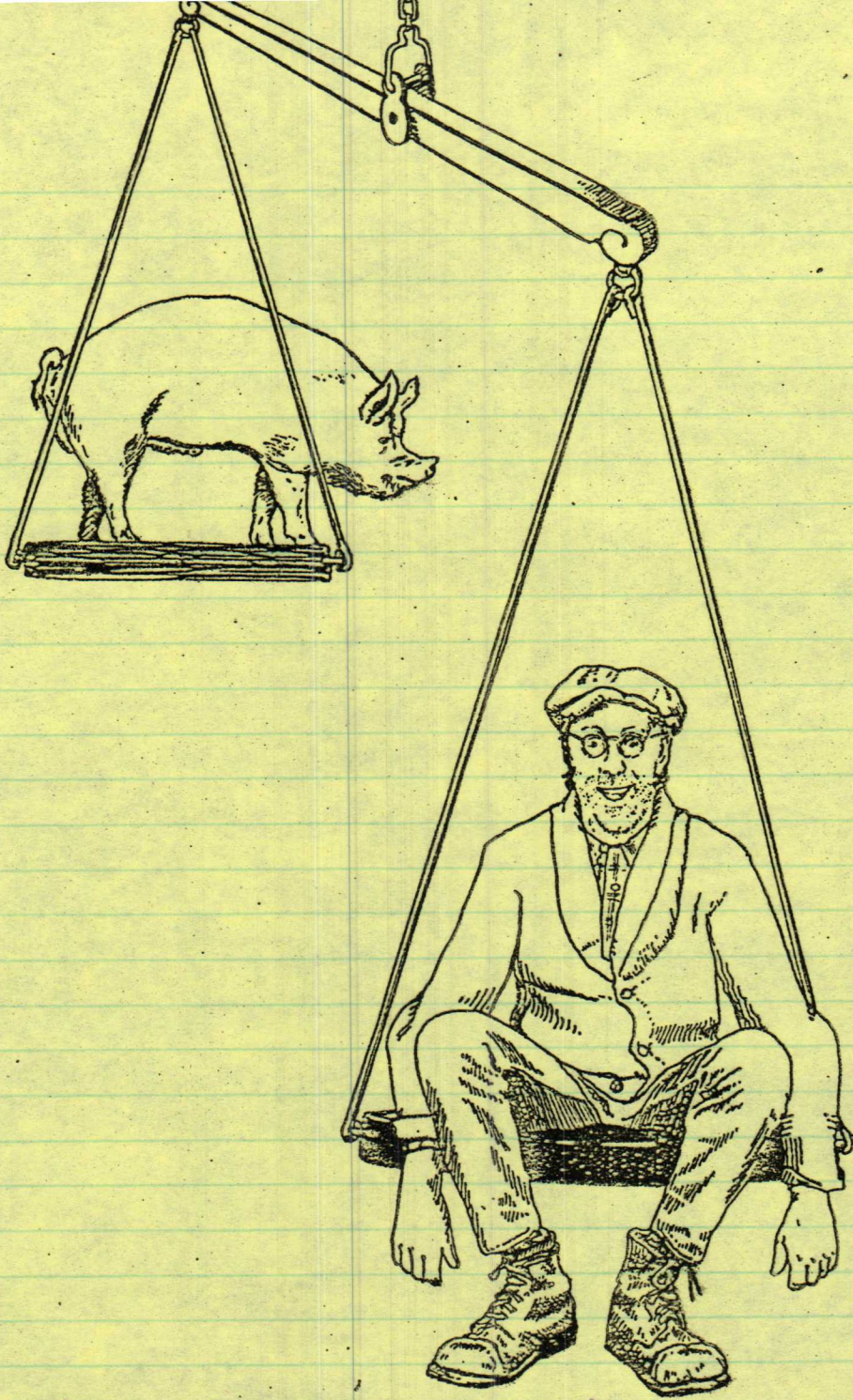
## Scaled Arrays

- Astrophysics  $\rightarrow$  change  $\nu_0$  without changing  $\theta_{\text{HPBW}}$ ?
  - spectral index
  - Faraday rotation
  - depolarization
- Intervals between some VLA bands  $\approx 3.3$   
(L  $\rightarrow$  C  $\rightarrow$  U)
- Ratios between VLA configurations  $\approx 3.3$
- Can have *similar*  $u$ - $v$  coverage at several frequencies



helps you make images with identical restoring beams and similar sensitivities to extended/compact structures at several frequencies. GOOD!





CALIBRATION

(Reference, Self, etc.....)



# What calibrations do you have to do?

Of lecture 5 factors,

VLA hardware automates

System Temp. Correction  
Round Trip Phase  
Geodetic effects

VLA staff calibrate

Pointing  
Baselines  
Clock setup  
Delays

You can calibrate  
(for polarimetry)  
  
(for spectroscopy)

{ "Leakage" terms  
Polarization position angle  
Bandpass ( $A, \phi$ )

You must calibrate

Flux density scale  
Position reference frame  
Short-term { amplitudes  
                  } phases

3C286 → Flux densities of unresolved calibrators, pol. p.a.

Unresolved calibrators)  
near your target source →

position reference frame  
short-term amplitudes/phases  
leakage terms in polarization  
bandpass



Q. Should I bother with external calibration if I know I will self-calibrate my source later?

A. Generally, yes, because external calibration tells you -

(a) flux scale

(b) position scale

(c) polarization p.a. scale

(d) instrumental polarization

(e) instrumental anomalies

(f) good and bad segments of phase stability

(g) characteristic timescale of atmosphere

last three may not be obvious from weak source data, though source may still self-cal if you can "latch" parameters.

POINT SOURCE "first guess" often works, but a good subset of externally calibrated data may converge faster + avoid false symmetries



# Calibration Strategy

PHASE — use unresolved calibrators from  
+ POSITION VLA manual (check for resolution  
+ AMPLITUDE notes in your config. at your  $\nu_0$ !)  
ON-CAL TIME DEPENDS ON  $\Delta\nu$ , CAL FLUX

FLUX DENSITY — use 3C286  
or 3C48

Don't use old flux densities of  
phase calibrators!

## Instrumental Calib.

Generally  $\geq 30^{\text{min}}$  cycle on strong source will do  
(but be prepared to discard data between cal  
if you find phase jumps)

## Atmospheric (Troposphere / Ionosphere) Calib.

NO GUARANTEES!

Cycle time depends on  
array, frequency (format)

Self-calibrate if you can

Choose strong unresolved calibrator as close to  
synthesis source as possible and HOPE it  
shows  $\Delta\phi \lesssim 20^\circ$  within and between scans.

\* Can estimate  $\tau$  gains for selfcal from nearby cal  
make preliminary model using "good" periods.



## Polarization Calib.

1. Observe 3C286 } for p.a. calibration  
3C138 } (essential)
2. Observe unresolved calibrator over  $\Delta$  (parallactic angle)  $\geq 90^\circ$  [ $\approx 3$  scans] to  $\rightarrow$  instrumental polarization (desirable) (synthesis calibrator may provide this data.)

N.B. Both may be difficult to schedule in short snapshot programs.

3. At <2GHz, observe polarized unresolved calibrator as close to synthesis source as possible  $\rightarrow$  changes in ionospheric Faraday rotation. (desirable)

Bandpass Calib.  $\rightarrow$  Strong source linefree.





## 40—50 GHz (Q Band)

- Use short time between reference calibrators
  - Dry night-time,  $\sim 15$  min
  - Bad days, need self-cal, SiO maser referencing
- Reference Pointing from 8 GHz (X Band)
  - Primary Beam only 1'
  - Update pointing ( $\sim 4$  min) every hour
- Measure Zenith Opacity (Tipping Scan)
  - About 10 minutes, once per run
- Only 10 antennas!



Affects resolution, sensitivity calculations

No "standard configurations" yet

Consult [http://www.nrao.edu/doc/vla/qband/qband\\_info.html](http://www.nrao.edu/doc/vla/qband/qband_info.html)



# STORMY WEATHER



- and what to do about it

Thunderstorms → poor phase stability  
Clear skies → ??

**OBSERVE** phase stability on  
**STRONG CALIBRATORS**  
**LONG BASELINES**

If poor ( $\geq 20^\circ$  between calibrators:)

- 1) SELFCAL LATER (if you can)
- 2) ADJUST TO LOWER- $V$  PROGRAM
- 3) SPEED UP CALIBRATOR CYCLE?  
(especially if calibrators near sources)





## Spectroscopy Strategies

(Details where they differ from continuum case)

- *Start* by specifying frequency  $\nu_0$ !
  - species, transition
  - Doppler corrections ( $z$ , motions of Earth ...)
  - check that you're in tuning range of system!
  - check for RFI (redshifted H I, galactic OH)
  - if project is  $\nu$ -agile (*e.g.* H $\alpha$ ), consider same instrumental parameters (sensitivity, pointing) as for continuum





## Spectroscopy Strategies, continued

There are two IF bandwidths to choose:

- Total  $\Delta\nu_{\text{tot}}$  across all channels Brinks, Uson
  - Consider total velocity range needed
  - Consider need for line-free channels
- Individual channel  $\Delta\nu_{\text{ch}}$ 
  - Sets velocity *resolution*
  - Usually sets bandwidth smearing  $\rightarrow$  small for individual channels!  $\Delta\nu/\nu_0 \sim \Delta v/c$  Uson
  - Coupled to  $\Delta\nu_{\text{tot}}$  via correlator design Brinks

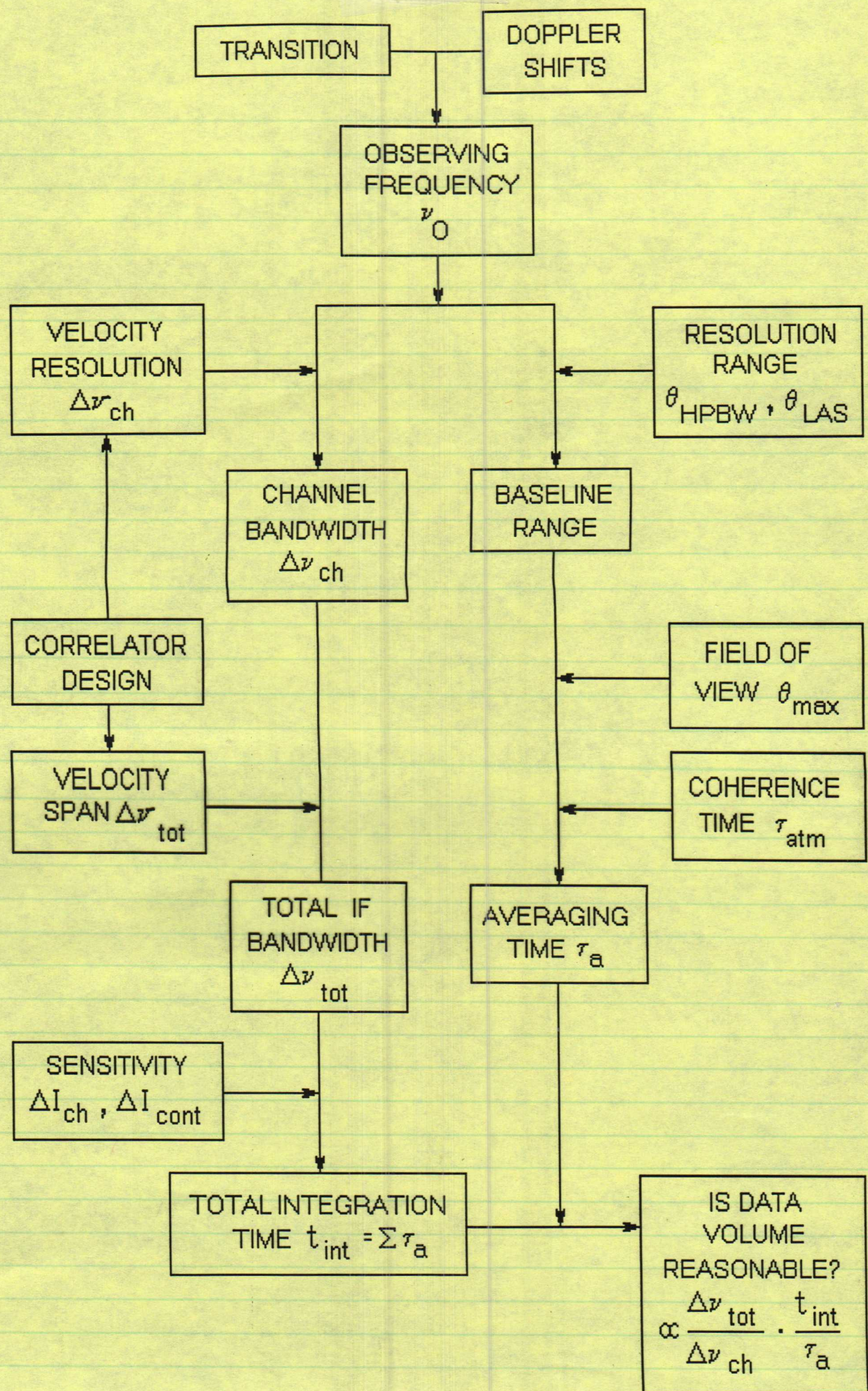




## Spectroscopy Strategies, continued

- Averaging time  $\tau_a$ 
  - No longer compare with bandwidth smearing!
  - Evaluate from time-average smearing alone
  - Consider dataset size ( $\propto t_{\text{int}}/\tau_a$ )
- Total integration time  $t_{\text{int}}$  Brinks, Uson
  - Consider sensitivity per line channel  $\Delta\nu_{\text{ch}}$
  - Continuum sensitivity in line-free channels?
  - Narrow  $\Delta\nu_{\text{ch}}$  may  $\rightarrow$  long  $t_{\text{int}}$ !
- Night-time astronomy? Brinks
  - compact arrays + narrow  $\Delta\nu_{\text{ch}}$   $\rightarrow$  more problems with far-out sidelobe responses to strong sources, e.g., active Sun.









## HINTS FOR PROPOSERS

1. Write concisely
2. Check catalog of VLA observations before writing in detail. (VLASORS)
3. Justify choices  $\left\{ \begin{array}{l} \text{CONFIGURATION} \\ \text{FREQUENCY} \\ \text{TOTAL TIME, etc} \end{array} \right.$
4. Think about observing and calibration strategy before submitting. ALLOW CALIBRATION TIME  $\geq 10\%$ !
5. Submit before deadline for first configuration needed



**Table 19-11**

**Near Term VLA Proposal Deadlines**

| Observing Dates             | Config | Proposal Deadline |
|-----------------------------|--------|-------------------|
| 19 Jan 1996 - 05 Feb 1996   | CnB    | 01 Oct 1995       |
| 09 Feb 1996 - 15 Apr 1996   | C      | 01 Oct 1995       |
| 26 Apr 1996 - 27 May 1996   | DnC    | 01 Feb 1996       |
| 31 May 1996 - 02 Sep 1996   | D      | 01 Feb 1996       |
| late Sep 1996 - 02 Dec 1996 | A      | 01 Jun 1996       |
| mid Dec 1996 - 30 Dec 1996  | BnA    | 01 Oct 1996       |





## Resources for VLA Proposal Planning

- VLA WWW Home Page

- <http://www.nrao.edu/doc/vla/html/VLA.html>
- VLA Observational Status Summary
- observation archive indexes
- recent L Band interference plots
- up-to-date Q Band information
- proposal submission information

- Observation planning software available by ftp:

- VLAPLAN
- VLASORS
- OBSERVE

NRAO  
Home





## VLAPLAN

- "This lecture in software"
- MS-DOS spreadsheet-like program
- you input imaging requirements
- it recommends VLA configurations
- it warns of parameter conflicts
- it advises how to resolve conflicts
- shows context-sensitive graphs
  - bandwidth smearing
  - time-average smearing
  - primary beam
  - visibility-baseline plots

Now ftp from `ftp.aoc.nrao.edu` in `/pub/vlaplan`.

Read `vlaplan2.doc` first.

Can access via VLA WWW Page mid-June 1995.





## VLASORS

- MS-DOS database and query program
- contains VLA Calibrator List
- contains VLA observation archives (*listing, not the data!*)

Now ftp from `ftp.aoc.nrao.edu` in `/pub/vlasors`.  
Read `read.me` first.





## OBSERVE

- The actual VLA schedule preparer
- Sun/IBM Unix systems
- Contains VLA Calibrator List
- Models on-line system accurately
- Can use to model exact calibration overhead
- Check drive times, limits, shadowing, etc.
- Check parallactic angle coverage
- **Some familiarization time required!!**

Now ftp from `ftp.aoc.nrao.edu` in `/pub/observe`.